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Deep learning representations for quantum many-body systems on heterogeneous hardware

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Abstract

The quantum many-body problems are important for condensed matter physics, however solving the problems are challenging because the Hilbert space grows exponentially with the size of the problem. The recently developed deep learning methods provide a promising new route to solve long-standing quantum many-body problems. We report that a deep learning based simulation can achieve solutions with competitive precision for the spin *J*1–*J*2 model and fermionic *t*-*J* model, on rectangular lattices within periodic boundary conditions. The optimizations of the deep neural networks are performed on the heterogeneous platforms, such as the new generation Sunway supercomputer and the multi graphical-processing-unit clusters. Both high scalability and high performance are achieved within an AI-HPC hybrid framework. The accomplishment of this work opens the door to simulate spin and fermionic lattice models with state-of-the-art lattice size and precision.

1. Introduction

Strongly correlated quantum many-body physics is one of the most fascinating research fields in condensed matter physics. When a large number of microscopic particles interact with each other, quantum entanglement is built among them and exotic physical phenomena emerge, such as (high-temperature) superconductivity [1], quantum Hall effects [2], quantum spin-liquid [3], etc. Solving these problems will greatly deepen our understanding of the basic laws of the natural world and guide us to find novel physical phenomena and new quantum materials.

Although the basic rules of quantum mechanics are known, solving strongly correlated quantum many-particle problems is still extremely challenging. This is because the Hilbert space of the solution grows exponentially with the size of the problem. Furthermore, although the perturbative methods are very successful for simulating weakly correlated material systems, they fail for the strongly correlated systems. Revealing the fascinating physical natures in quantum many-body systems mainly relies on the non-perturbative numerical methods, such as exact diagonalization (ED), the quantum Monte Carlo method (QMC) [4] and the density matrix renormalization group (DMRG) [5].

However, these methods all have serious limitations: e.g. the computational cost of ED grows exponentially with the system size, and therefore the system size of the ED method is limited to less than 50 sites [6]. QMC suffers from the notorious sign problem for fermionic and frustrated systems [7]; and DMRG is limited to 1D or quasi-1D systems and does not work well for higher dimension systems [8]. To maintain the same accuracy, the computational costs of DMRG grow exponentially with the width of the lattice. Thus far, the width of DMRG simulation is limited to $L \approx 12$ [9]. Very recently, the so-called tensor network methods, e.g. the projected entangled-pair states (PEPSs) method [10] have been developed, which can simulate fermionic and frustrated systems. For example, the PEPS can solve the frustrated J1–J2 model to a high accuracy with open boundary conditions (OBCs) [11, 12]. However, the periodic boundary condition (PBC) usually has smaller boundary effects than OBC, and is therefore more suitable for simulating quantum many-body systems. However due to the high scaling to the bond dimension $O(D^{18})$, there is no report of PEPS simulation on PBC with the bond dimension $D \ge 6$, which is still too small to catch the essential physics of quantum many-body models.

Recently, the rapid progress of artificial intelligence powered by deep learning [13, 14] has attracted the attention of the scientific community on applying deep learning to solve scientific problems. For example, neural networks are used to solve differential equations [15], accelerate molecular dynamics [16], predict proteins' 3D structures [17], control nuclear fusion [18], and so on. There are also great efforts in applying deep learning methods to study quantum many-body problems.

Compared to traditional deep learning tasks such as classification, there are some major challenges in solving quantum many-body problems via neural networks, because one has to obtain an extremely high accuracy ground state in the exponentially large Hilbert space:

- The neural network's generalization ability should be high enough to represent the quantum state in the exponentially large Hilbert space.
- Double precision of the network parameters is mandatory.
- The ground energy should be the global minimum of the energies. The first-order-gradient based optimizers like Adam, SGD, etc are not efficient, as they can be easily trapped into local minimal. Here, a second-order natural-gradient-like method, such as the stochastic reconfiguration (SR) method is used.
- Finding the solution in the exponentially-large Hilbert space requires an extremely large amount of MCMC samples, which is also required for precise SR optimization.

Great efforts have been made to solve quantum many-body problems via deep learning methods [19, 20]. In 2017, Carleo *et al* solved the Heisenberg model via a restricted Boltzmann machine (RBM), with 323 200 network parameters and obtained rather high precision results on the 10×10 square lattice [21]. For the frustrated system such as the spin-1/2 J1–J2 Heisenberg model, complex network parameters are necessary. In 2018, a single-layered convolutional neural network (CNN) with 11 009 parameters was reported [22] to solved the frustrated J1–J2 model with satisfactory precision. To further improve the energy precision on the 10×10 lattice, the Gutzwiller projection fermionic wave-function with the RBM [23] and the deep CNN with a sign rule [24] were used. In 2021, on the Fugaku supercomputer, the pair product states with a RBM has achieved high accuracy on the lattice as large as 18×18 [25]. In 2022, by increasing the deep CNN parameter number to 106 529, the energy precision is greatly improved and the lattice size is increased to 24×24 [26]. Since that various quantum states can be represented by CNN based wavefunctions [27], the quantum state representation is named the convolutional neural quantum state (CNQS).

The Fermion models are even more challenging. In 2019, by employing CNN based Jastrow and sign corrections, the spinless Fermions model was investigated on a 10×10 lattice [28]. There are several investigations for the Fermi–Hubbard model. In 2019, by employing a fully-connected neural network (FCNN) in the Slater determinant, the model was studied on a 4×4 lattice [29]. In 2021, a FCNN was used as the determinant free wavefunctions to study the model on a 6×6 lattice [30]. In 2022, the RBM ansatz solved the Hubbard model on the lattice as large as 4×16 [31].

In this work, we benchmark our methods on two important and representative models, namely the J1-J2 frustrated spin model and the *t*-*J* fermion model. Due to the quantum correlation, the degeneracy of the ground state is broken. However, there could be many competing states that have energies very close to the ground state energy. Therefore these models are extremely challenging. Both models are investigated on the rectangular lattices with PBC. We firstly optimize the CNN wavefunction through SR, then the wavefunctions are further optimized through a Lanczos step [32]. We develop an hybrid artificial intelligence-high performance computing (AI-HPC) framework to implement the optimizations, and achieve high scalability and high performance on two typical HPC platforms, the new generation Sunway supercomputer and the multi graphical-processing-unit (GPU) clusters. Furthermore, the optimization results show that the CNN based wavefunctions can achieve competitive energy precision on unprecedented lattice sizes.

The J1–J2 model is a candidate model for the quantum spin liquids [12, 25], and the Hamiltonian reads:

$$\hat{H} = J1 \sum_{\langle i,j \rangle} \mathbf{s}_i \cdot \mathbf{s}_j + J2 \sum_{\langle \langle i,j \rangle \rangle} \mathbf{s}_i \cdot \mathbf{s}_j \tag{1}$$

where $\langle i,j \rangle$ and $\langle \langle i,j \rangle \rangle$ indicate the nearest and next-nearest neighbouring spins pairs. **s**_{*i*} is the spin operator on the *i*th site. We set J1 = 1 and J2 = 0.5 throughout the investigations.

The *t*-*J* is a basic model for the superconductivity [33], and the Hamiltonian is:

$$\hat{H} = -t \sum_{\langle i,j \rangle,\sigma} (c^{\dagger}_{i,\sigma}c_{j,\sigma} + h.c) + J \sum_{\langle i,j \rangle} \left(\mathbf{s}_i \cdot \mathbf{s}_j - \frac{n_i n_j}{4} \right)$$
(2)

where $\langle i,j \rangle$ indicate the nearest neighbouring pairs. The operator $c_{i,s}^{\dagger}$ creates an electron of spin s on site *i*, s_i and n_i are the electron spin moment and charge density operators on site *i*. We encode the Fermions into spins via Jordan–Wigner transformation [34]. In the simulations, t = 1, J = 0.4 and the hole doping $n_h = 0.125$ are used.

2. Methods

2.1. The framework of optimizing the neural network

Taking the quantum spin model as an example, a quantum many-body state is represented by a superposition of the spin configurations,

$$|\Psi\rangle = \sum_{S} W(S)|S\rangle \tag{3}$$

where $|S\rangle = |s_1^z, s_2^z, \dots, s_N^z\rangle$ is a set of spins with one on each site of the lattice, and *N* is the total number of sites. If the degree of freedom on each site is *k*, the Hilbert space (i.e. the number of $|S\rangle$) of the problem is k^N . The weight of the spin configuration W(S) is represented by a neural network. The network parameters are optimized to determine the ground state of the system, i.e. the state of the lowest energy $E_{g,s} = \min\langle \Psi \hat{H} \Psi \rangle / \langle \Psi | \Psi \rangle$, where \hat{H} is the Hamiltonian of the system.

The self-learning procedure for optimizing the neural network is depicted in figure 1. First, Markov-Chain-Monte-Carlo (MCMC) is performed according to $|W(S)|^2$. When collecting a sample, the forward of the neural network gives local energy E_{loc} and the backward of the neural network gives local derivative O_{loc} . Secondly, the gradients and the covariance matrix needed for the SR optimization method [35] are calculated. Finally, the network parameters are updated, and the values for updating parameters are δ .

After the SR minimization, the wavefunctions can be further optimized by a Lanczos step:

$$|\Psi_p\rangle = \alpha_p |\Psi_{p-1}\rangle + \beta_p |\Psi_{p-1}^{\perp}\rangle, \tag{4}$$

where α_p and β_p are the parameters to be determined, and $|\Psi_0\rangle$ is the variational wavefunction after SR optimization. $|\Psi_p^{\perp}\rangle$ is orthogonal to $|\Psi_p\rangle$: $|\Psi_p^{\perp}\rangle = \frac{1}{\sigma_p}(\hat{H} - E_p)|\Psi_p\rangle$, where the energy $E_p = \langle \Psi_p | \hat{H} | \Psi_p \rangle$ and the variance $\sigma_p^2 = \langle \Psi_p | \hat{H}^2 - E_p^2 | \Psi_p \rangle$. For the state $|\Psi_p\rangle$ with energy E_p and variance σ_p , it is easy to prove that $E_p \approx E_{\text{exact}} + \text{const.} \times \sigma_p^2$. Here we consider the average energy per site $E = E_p/N$ and the variance per site σ^2/N : $E \approx E_{\text{exact}} + \text{const.} \times \sigma^2/N$. [32]

2.2. Neural network method details

2.2.1. Neural network structure

To meet the strictly demanding requirement, we develop two deep CNN structures for the spin models and fermion models, which are denoted as CNN1 and CNN2 respectively. The computational complexity of CNN is much lower compared to the fully connected structure. By taking advantage of translational invariance, the CNN can scale to very large lattices.

The structure of CNN1 is depicted in figures 2(a) and (b), and the network is built by stacking the building block denoted in figure 2(a) six times [36]. A building block consists of two-dimensional convolution and one-dimensional maxpooling and transposed-convolution. To maintain the dimensions, paddings are employed on the input spin lattice and between two building blocks. The padding scheme is based on the PBCs. The final outputs are the products of the neurons, which are the wavefunction coefficients for the input spin configurations.

The structure of CNN2 is depicted in figures 2(c) and (d). CNN2 originates from CNN1, with two major modifications: (1) the input spin lattice is processed by an embedding layer; (2) the one-dimensional maxpooling is performed with stride one. To maintain the dimensions, padding is performed by copying the first several neurons to the last. The deep structure is built by stacking the building block in figure 2(c) six times. Finally, with a convolution operation, the channel number is decreased to one, the final output is the product of the neurons.

The deep CNN structures used in this work have several important differences compared to other CNN structures for quantum many-body problems [21, 24, 28]. First, the nonlinearity in our deep CNN is





induced by the maxpooling, instead of traditional activation functions. The maxpooling picks up the most important degree of freedom in a convolution filter, which is similar to the coarse-grained process in a renormalization group theory [37]. Second, the wavefunction coefficients are generated by the products of neurons, thus the CNN can give the ± 1 signs within real network parameters, which differs from the exponential function in RBM based structures.



2.2.2. Neural network wavefunction representation

The CNN1 structure in this work is based on the deep CNN previously reported in [26, 36], and the wavefunction is preconditioned by the Marshall-sign-rule (MSR)[38, 39]:

$$\tilde{W}(S) = (-1)^{\mathrm{MA}} W_{\mathrm{CNN1}}(S), \tag{5}$$

where MA is the magnetization on the equivalent sublattice A. Although the MSR is only exact for the case of J2 = 0, however, because the CNN1 is able to give the ± 1 signs, it is able to correct the MSR for large J2.

Enforcing symmetries can significantly reduce the optimization difficulty [40]. In the case of J2 = 0.5, the final wavefunction coefficient has an enforced rotational symmetry on the square lattice [24]:

$$W(S) = \sum_{i} \tilde{W}(\hat{T}^{i}S), \tag{6}$$

where \hat{T} is the spin rotation operator and i = 0, 1, 2, 3.

Based on the structure of CNN1, we design CNN2 to solve the *t-J* model. To encode the Fermions into spins, Jordan–Wigner transformation is used. Figure 3 denotes the spin ordering for the JW transformation on 4×4 square lattice. We have compared several spin orderings on the 8×8 square lattice, and the spin ordering denoted in figure 3 gives the lowest variational energy.

There are three degrees of freedom in each site for the *t-J* model, which correspond to no-occupation, one-occupation with spin up and spin down. The Hilbert space of the *t-J* model is much larger compared to spin models, thus a higher representation ability of the CNN is required. To enhance the representation ability, an embedding layer is employed to transfer the input of each degree of freedom to a trainable two-element vector. Even though the original Hamiltonian of the *t-J* model has rotational symmetry, the JW transformation breaks this symmetry, and we do not enforce any additional symmetry of the CNN wave-function, and the final wave-function coefficient is directly generated from the CNN2: $W(S) = W_{\text{CNN2}}(S)$.

2.2.3. Transfer learning

For the J1-J2 model, direct training of the model in large lattice starting from random parameters is very difficult. The convolution operation is intrinsically scalable for different lattice sizes. Furthermore, the energy convergence on a small lattice is fast, as the lattice size increases, the ground energy will converge with respect to the lattice size. Initially the network is trained on 6×6 lattice from randomly initialized parameters. The network parameters are then checkpointed and used for optimizing the larger 10×10 system as the pretrained model. With multiple stages of transfer learning, we finally increased the lattice size to 36×36 and obtained a good initial energy. Thanks to transfer learning, the local optimizations are avoided and the training steps for large lattices are significantly reduced.

2.2.4. Parallel initial state selection

For the *t*-*J* model, a proper initial model parameter and the initial spin configuration are beneficial for avoiding local optimizations, and therefore crucial for fast energy convergence. Here we calculate the energy



of a randomly initialized CNN by performing MCMC sampling, assuming that the CNN with lower initial energy will have a better convergence after SR optimizations. With a preselection stage, the CNN parameters together with the initial spin configuration that has the lowest energy result are selected. After the initial state selections, the optimization steps are significantly reduced especially on the lattice as large as 12×12 .

2.3. AI-HPC hybrid parallel optimization framework

To optimize the CNN wavefunctions in an efficient and scalable way, we propose an AI-HPC hybrid framework to implement the algorithm introduced in figure 1, and the framework is depicted in figure 4. Overall, the AI-HPC hybrid framework can be divided into two parts: MCMC sampling and SR. The first part can be seen as data parallelism, where different processes hold the same model parameters but compute different input data. The second part is responsible for handling MCMC samples and computing the parameter update δ of network parameters in SR by constructing a large covariance matrix.

2.3.1. Process- and thread-level parallel MCMC

Different from the distributed data parallel training in conventional deep learning tasks, the proposed AI-HPC framework only holds the same model state, while it replaces training data with on-the-fly MC sampling. In principle, importance sampling in the Hilbert space is achieved by multiple independent Markov chains. Considering that the MC sampling tasks are intrinsically parallel, they can be distributed across all participating processes, where the parallel execution among the 4 processes is pictured in figure 4(a). Inside each process, there is an independent chain of MC sampling, which generates E_{loc} and O_{loc} with model forward and backward computations. In the figure, each process produces *B* samples, where *R* equals the number of network parameters. The input data is naturally distributed along with Markov chains. Implementing the process-level parallel sampling only requires broadcasting the initial parameter number and the parameter update.

The MCMC sampling is time sequential, and numerous state transitions exist between two collected samples. The state transition along the Markov chain requires little computation, which leads to significant resource under-utilization, especially for today's powerful heterogeneous devices. In this case, an alternative by managing multiple independent chains in one process is proposed, as depicted in figure 4(b). In each step, one sampling step from many chains increases the batch size during the model computation. The CNN computation is further divided into multiple computing layers and then offloaded onto heterogeneous many-core processor with modest thread-level parallel optimization. The repeated CNN execution with varying lengths can be organized with the fixed-length batch to improve performance. Additionally, such method theoretically increases the sample independence, which may help faster model convergence comparing to sampling from a single chain.

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The flexible parallel MCMC scheme (i.e. MPI-parallel among different processes and batch-parallel among independent chains) provides an alternative to navigate the aforementioned initial state selection in section 2.2.4. To adapt to the two-level MCMC sampling, the selection paradigm is described in figure 4(d). The parallel processes is designed to find suitable initial model parameters, while the chain batch inside each process aims to find the best initial spin lattice. Taking the advantage of HPC infrastructure to simultaneously examine millions of sampling results, it dramatically offsets the difficulty in finding a reasonable initial configuration in the exponentially large Hilbert space.

2.3.2. Distributed SR computation

With sufficient samples collected from MCMC, the values for updating network parameters δ are obtained through SR. The procedure for computing δ includes three steps: (1) adjusting the data format; (2) constructing the covariance matrix; and (3) solving a system of linear equations.

After MCMC sampling, the input for the SR procedure is the evenly distributed among all participating processes. These samples are then organized in a 2D-mesh style. For *P* processes, the collected samples are divided into \sqrt{P} blocks. Naturally, the processes are split into \sqrt{P} groups, where each group contains \sqrt{P} processes. The data block is scattered into corresponding processes within the group.

Figure 4(c) denotes an example of 4 processes (Proc-0 and Proc-1 in group-1, Proc-2 and Proc-3 in group-2). The block exchange between 2 processes can be illustrated by swapping blocks of @ and @ in group 1 (@ and @ in group 2). As depicted in the figure, for a CNN with the parameter number *R*, it generates the 2D-mesh distributed matrix [4 *B*, *R*]. The following covariance matrix [*R*, *R*] is constructed in parallel. The final δ is obtained by combining the matrix with the first-order gradients of the energy. Similar to data parallelism training, all processes shares the same δ by MPI broadcast.

The scalability of SR is limited on constructing and solving the covariance matrix. In previous investigations, small network parameter number achieves moderate energy precision [36]. In this work, the network parameter number is further increased to the magnitude of 10⁵. With the help of modern parallel programming paradigm and high performance heterogeneous devices, accurately constructing and storing the full covariance matrix is still feasible. However, there still exists scalability issue as the parameter number continues to increase. One solution is to adopt approximate solutions, such as the sparse distributed solver as introduced in NetKet [41] and hybrid low-rank natural gradient method in [42]. Investigating the performance of these highly scalable sparse algorithms is one of our future directions.

2.3.3. Hybrid implementation in AI and HPC

Figure 4(e) depicts the proposed AI-HPC software stack in solving CNQS. In this work, CNQS is built by a series of common deep learning operators, such as *Conv*, *Deconv*, *Maxpool* and *Embedding*.

The gradients of CNQS are obtainable through the MCMC. As introduced in section 2.1, the forward and backward calculations of the CNN give the local energy and the local derivative during the MCMC. With the gradients, it is straightforward to use optimizers, such as SGD, Adam, etc. The forward and backward computation of CNN, as well as the optimizers are supported by mainstream deep learning libraries, such as TensorFlow and PyTorch, etc. The SR method is handled by the MPI and ScaLAPACK, which further supports heterogeneous devices through the MAGMA library.

The computation of CNN can be significantly accelerated by heterogeneous hardware, such as Intel Xeon Phi, NVIDIA (AMD) GPUs, sw26010pro CPUs, etc. The sw26010pro many-core processor is the upgraded version of sw26010 released with Sunway TaihuLight [43–45]. Taking sw26010pro as an example, there are six core groups on one chip. In each core group, there is one MPE (management process element) that acts as control elements and 64 CPEs (computing process elements) that act as computing elements. By offloading the computation into the CPEs, a high acceleration ratio is achieved for deep learning operators, e.g. *Conv* and *Deconv* [26].

Thanks to the modern programming paradigm and flexible libraries (i.e. sw/cu/roc-dnn or BLAS), the optimization of CNQS can be easily adapted onto both the traditional CPU and diverse heterogeneous accelerators.

3. Results

In this section, we demonstrate the computational efficiency and parallel scalability of the proposed hybrid AI-HPC framework on two typical heterogeneous systems. Specifically, two optimization algorithms (i.e. MCMC+SR and Lanczos elaborated in this paper) are thoroughly evaluated on the new generation of Sunway supercomputer and NVIDIA A100 cluster, respectively. Meanwhile, by solving two long-standing quantum models: the *J*1–*J*2 model and *t*-*J* model, the competitive results of variational energies demonstrate the effectiveness of the scalable deep learning method.



3.1. Performance and Scalability on heterogeneous architecture

The optimization of the CNN based wavefunction is achieved in two stages: first MCMC+SR optimization, and then Lanczos optimization. Here, we show that the computation of CNNs can be significantly accelerated by the heterogeneous cores, and the optimization of CNN based wavefunctions is perfectly scalable on the HPC platform. For example, MCMC+SR has high scalability among up to 40 million heterogeneous cores on the new generation Sunway supercomputer, and the Lanczos optimization has perfect scalability demonstrated in multi-GPU systems.

3.1.1. Performance enhancements by CPEs

For the sw26010pro CPU delivered with the new generation Sunway supercomputer, most computing power for each core group is provided by the 64 CPEs. Therefore it is important to utilize the CPEs to achieve high performance. Taking the compute-intensive operators used in CNN1 and CNN2 as examples, the many-core acceleration ratios for *Conv2D*, *Conv2DBackpropInput* and *Conv2DBackpropFilter* are $538 \times$, $211 \times$ and $505 \times$, respectively. Comparing to the compute-intensive operators, the many-core acceleration ratios of memory-intensive operators are limited due to the inability to achieve the same high CPE utilizations. The many-core acceleration ratio reaches 33.21–35.93 for *Tile* and 34.2–44.8 for *Slice*.

With the performance optimized operators, the overall acceleration ratio achieves considerable performance improvement over original MPE version. The many-core acceleration ratio for the CNN1 with 106 529 and 421 953 parameters are $90 \times$ and $130 \times$, respectively.

3.1.2. Performance and scalability results

For the MCMC+SR implemented on Sunway HPC, the elapsed time for one optimization step with respect to the core number is depicted in figure 5(a). In this case, J2 = 0.5 and L = 10, the total sample number is about 5×10^6 and the network parameter number is 106 529. Under 40 000 processes, the elapsed time of one MCMC+SR step requires 1053 s with 64 CPEs acceleration, while the elapsed time for the MPE version is over 39 258 s. Therefore an acceleration ratio of approximately 37 times is achieved by utilizing the CPE cluster, compared to the MPE only. The MCMC+SR can be easily scaled to the whole system, with a maximum of 608 400 processes. It reports nearly $10 \times$ throughput improvement and achieves 63% parallel efficiency when scaling to nearly 40 million cores.

For the Lanczos optimization, it is necessary to calculate the high order expectation of Hamiltonian like $\langle \hat{H}^2 \rangle$ and $\langle \hat{H}^3 \rangle$. Figure 5(b) depicts the elapsed time for calculating $\langle \hat{H}^2 \rangle$ with respect to the NVIDIA A100

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CUDA core number. In this case $J^2 = 0.5$ and L = 8, the total sample number is 30 240 and the total number of spin configurations is on the order of magnitude of $30 \, 240 \times L^4$. Different from the SR stage for handling the distributed covariance matrix, the Lanczos optimization only requires substantial CNN computation, which incurs little communication. Consequently, the forward calculations of all spin configurations are perfectly scalable to all the GPUs. As depicted by the figure, the parallel efficiency on 995 328 CUDA cores (144 GPUs) is 94%. In addition to the high scalability, for the double precision calculation of CNN wavefunctions, the speedup ratio of 55 296 CUDA cores (8 GPUs) to 640 CPU cores is 6.23.

Therefore, the optimization of CNN based wavefunctions has a high scalability and can achieve high acceleration ratio on heterogeneous systems.

3.2. Simulation results

3.2.1. Ground state energies

Based on the linear relationship between energy and variance introduced in section 2.1: $E \approx E_{\text{exact}} + \text{const.} \times \sigma^2/N$, figure 6(a) reveals the energy extrapolations achieved by CNN1 within 106 529 parameters for the *J*1–*J*2 model, and figure 6(b) reveals the energy extrapolations achieved by CNN2 within 113 815 parameters for *t*-*J* model. Note that the extrapolated values are used only for estimation purposes, as only two data points are used.

As depicted by figure 6(a), for the J1-J2 model in the maximal frustration region J2 = 0.5, the variational energies on the 10×10 lattice for p = 0 and p = 1 are -0.497168 and -0.497468 respectively, and the extrapolated energy is -0.497752. Furthermore, on the 12×12 lattice, the variational energies for p = 0 and p = 1 are -0.496636 and -0.496989 respectively, and the extrapolated energy is -0.497341.

As depicted by figure 6(b), for the *t*-*J* model with hole doping $n_h = 0.125$, the variational energies on the 12×8 lattice for p = 0 and p = 1 are -0.608793 and -0.6209887 respectively, and the extrapolated energy is -0.642031. On the 12×12 lattice, the variational energies for p = 0 and p = 1 are -0.622963 and -0.632605 respectively, and the extrapolated energy is -0.648179. From above results, we see that the Lanczos step can further improve the ground state energy.

The CNN1 used in this work has high quantum state representation ability, and therefore is more efficient comparing to other kinds of neural networks [46]. For example, for the 10×10 lattice with J2 = 0.5, the ground state energy obtained by the CNN1 with 16 443 parameters without Lanczos step (i.e. p = 0) is $-0.496\,687$, which is lower than -0.4960 obtained by the GNN-2 and the -0.4957 obtained by the lattice convolutional network (LCN) reported in [46]. Remarkably, the number of parameters of both GNN-2 and LCN is on the order of a million, which is significantly higher than that of CNN1.

3.2.2. Comparing to previous results

Here we present the competitive energy results of the *J*1–*J*2 model and *t*-*J* model achieved in this work, and compare them to other state-of-the-art results. The energies are obtained by the CNN wavefunctions with a Lanczos step.

For the *J*1–*J*2 model, the energy values achieved by CNN1 with 106 529 parameters for various *J*2 and lattice sizes are listed in table 1. The energies are obtained by CNN1 optimized by MCMC+SR, and a Lanczos step. Specifically, in the maximal frustration region $J_2 = 0.5$, the convergence of energy with respect to the square lattice size *L* is depicted in figure 7 by red dots. In the figure, the solid line is fitted with the function $E = a/L^3 + b$. Other state-of-the-art results are also shown in the figure for comparison. When L = 10, the

Description	0.46	0.48	0.50	0.55	0.60
10×10	-0.50744	-0.50231	-0.49747	-0.48670	-0.47839
12×12	-0.50697	-0.50183	-0.49699	-0.48603	-0.47715
14×14	-0.50675	-0.50159	-0.49674	-0.48581	-0.47678
16×16	-0.50662	-0.50147	-0.49659	-0.48565	-0.47656
18 imes 18	-0.50651	-0.50139	-0.49651	-0.48557	-0.47652

Table 1. Energy values for various *J*2 values and lattice sizes, achieved by CNN1 with 106 529 parameters. The values are obtained by the Lanczos step with p = 1.



energy in this work is -0.497468, which has a small distance comparing to the -0.497629 achieved by the PP+RBM method [25]. Increasing CNN parameter number and more than once independent optimization can further improve the energy precision. However, because of transfer learning, the energy obtained in this work for L = 18 is -0.496513, which is 4.5×10^{-4} lower than the -0.496275 reported in [25].

To date, there are no reference ground state energies for the *t-J* with PBC, therefore we compare the results to those of OBC calculated via PEPS in [47]. The parameter number of CNN2 is 113 815. On 8×8 lattice, the energy achieved by CNN2 is -0.60958, which is 3×10^{-3} higher than that reported in [47]. On 12×12 lattice, the energy achieved by CNN2 is -0.63261, which is 3.8×10^{-3} lower than that reported in [47]. We would like to note that the energies of different boundary conditions cannot be compared directly, which may have small differences. The results show here are only a demonstration of the effectiveness of CNN2 for fermionic lattice systems.

4. Discussion and outlook

In this work, we report simulations of challenging quantum many-body problems that combine the state-of-the-art deep-learning method and efficient implementation on the heterogeneous computational platform. We have obtained the ground state energies of the J1-J2 model and t-J model with accuracy competitive to current state-of-the-art results. With this ability, we are able to simulate a large class of important physical models with high accuracy to make confident conclusions about the physics. The method therefore opens up a new promising path to solve the extremely important and challenging problems that have plagued people for more than half a century, and would help us to understand exotic physical phenomena, such as quantum spin liquids , high temperature superconductivity [48], supersolid [49], heavy fermions [50], fractional quantum Hall effects, [51–53] and many more, which is not only essential for the understanding of fundamental physics but also have many important applications.

On the other hand, this work demonstrated the effectiveness of solving the quantum many-body problem via deep learning methods on the supercomputer platforms, which is completely different from traditional machine learning tasks. These applications represent a large class of scientific problems that are more challenging in the representation ability of the network and the accuracy requirements of the results. It also puts forwards higher requirements for efficient optimization algorithms and implementations. This

framework may apply to other problems, e.g. the simulation of quantum circuits on classic supercomputers. Currently tensor network methods have shown high efficiency for quantum circuit simulations on supercomputers [45] on the lattice as large as 10×10 . The scalable neural network based quantum state representation may be capable of performing quantum circuit simulations for an even larger number of qubits.

Our MCMC+SR optimization framework is not limited to Sunway, and it can be easily ported to other supercomputing platforms. However, as the computational power increases, the overall application performance will be limited by the gap between the computing capability and the memory access bandwidth. Here we take the computational power v.s. memory bandwidth ratio (FLOP/Byte) to measure the potential performance. Because the single precision does not meet the requirements of achieving faithful ground state energies, we focus here on the double precision FLOP/Byte. With the double precision support of tensor cores, the FLOP/Byte ratio on an A100 GPU is 9.56 (19.5 TFLOPS/2039 GB/s = 9.56 FLOP/Byte). The double precision FLOP/Byte ratio on a Fujitsu A64FX CPU is 3.3 (3.3792 TFLOPS/1024 GB/s = 3.3 FLOP/Byte). Considering that the performance of the LDM used in sw26010pro is not competitive with the performance of HBM2 used in A100 and A64FX, therefore the performance of our framework can be further boosted on other HPC systems.

Data availability statement

The data that support the findings of this study are openly available at the following URL/DOI: https://doi.org/10.5281/zenodo.6976345 and https://doi.org/10.5281/zenodo.6975696.

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